

Math 22: Linear Algebra and Applications

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Placement Test

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1 Linear Equations in Linear Algebra

1.1 Systems of Linear Equations

Definition 1.1.1 (Linear Equation)

A **linear equation** in the variables x_1, x_2, \dots, x_n is an equation that can be written in the form

$$a_1x_1 + a_2x_2 + \dots + a_nx_n = b$$

where a_1, a_2, \dots, a_n and b are constants, called the **coefficients** and **constant term**, respectively.

For example, $3x_1 - 2x_2 + 5x_3 = 7$ is a linear equation in the variables x_1, x_2, x_3 with coefficients 3, -2 , 5 and constant term 7.

Definition 1.1.2 (System of Linear Equations)

A **system of linear equations** is a collection of one or more linear equations involving the same set of variables.

Definition 1.1.3 (Solution)

A **solution** to a system of linear equations is an assignment of values to the variables that satisfies all equations in the system simultaneously.

1.2 Row Reduction and Echelon Forms

1.3 Vector Equations

1.4 The Matrix Equation $Ax = b$

1.5 Solution Sets of Linear Systems

1.6 Linear Independence

1.7 Linear Transformations; Matrix Representations

2 Matrix Algebra

2.1 Matrix Operations

2.2 The Inverse of a Matrix

2.3 The Inverse Matrix Theorem

2.4 Coordinates, Dimension, and Rank

3 Determinants

3.1 Introduction to Determinants

3.2 Properties of Determinants

4 Vector Spaces

4.1 Vector Spaces and Subspaces

4.2 Null Space, Column Space, and Linear Transformations

4.3 Linearly Independent Sets; Bases

4.4 The Matrix of a Linear Transformation

4.5 Change of Basis / Composition of Linear Transformations

4.6 Applications: Markov Chains

5 Eigenvalues and Eigenvectors

5.1 Eigenvectors and Eigenspaces

Definition 5.1.1 (Eigenvector and Eigenvalue)

Let A be an $n \times n$ matrix. A nonzero vector $\mathbf{v} \in \mathbb{R}^n$ is called an **eigenvector** of A if there exists a scalar λ such that

$$A\mathbf{v} = \lambda\mathbf{v}.$$

The scalar λ is called the **eigenvalue** corresponding to the eigenvector \mathbf{v} .

Theorem 5.1.2

The eigenvalues of a triangular matrix are the entries on its main diagonal.

Proof. For simplicity, let's consider the 3×3 matrix. If A is upper triangular, then $A - \lambda I$ has the form

$$\begin{bmatrix} a_{11} & a_{12} & a_{13} \\ 0 & a_{22} & a_{23} \\ 0 & 0 & a_{33} \end{bmatrix} - \begin{bmatrix} \lambda & 0 & 0 \\ 0 & \lambda & 0 \\ 0 & 0 & \lambda \end{bmatrix} = \begin{bmatrix} a_{11} - \lambda & a_{12} & a_{13} \\ 0 & a_{22} - \lambda & a_{23} \\ 0 & 0 & a_{33} - \lambda \end{bmatrix}$$

The scalar λ is an eigenvalue of A if and only if $A - \lambda I$ is not invertible, which occurs if and only if the determinant is zero:

$$\det(A - \lambda I) = 0.$$

□

Lemma 5.1.3

Let A be a $n \times n$ matrix. Then A is invertible if and only if 0 is not an eigenvalue of A .

Theorem 5.1.4

If v_1, v_2, \dots, v_k are eigenvectors of a matrix A corresponding to distinct eigenvalues $\lambda_1, \lambda_2, \dots, \lambda_k$, then the set $\{v_1, v_2, \dots, v_k\}$ is linearly independent.

5.2 The Characteristic Equation

Example 5.2.1

Find the eigenvalues and eigenvectors of the matrix

$$\begin{bmatrix} 2 & 3 \\ 3 & -6 \end{bmatrix}$$

Solution.



Definition 5.2.2 (Determinant)

The **determinant** of a square matrix A is a scalar value that can be computed from the elements of A and encodes certain properties of the linear transformation described by A . The determinant is denoted as $\det(A)$ or $|A|$.

Example 5.2.3

Compute $\det(A)$ for the matrix

$$\begin{bmatrix} 1 & 5 & 0 \\ 2 & 4 & -1 \\ 0 & -2 & 0 \end{bmatrix}$$

Solution.



5.3 Diagonalization

5.4 Eigenvalues and Linear Transformations

5.5 Iteration Method for Approximating Eigenvalues

6 Orthogonality and Least Squares

6.1 Inner Product, Length, and Orthogonality

6.2 Orthogonal Sets

6.3 Orthogonal Projections

6.4 The GramSchmidt Process / Least Squares Problems

7 Symmetric Matrices and Quadratic Forms

7.1 Diagonalization of Symmetric Matrices

7.2 Singular Value Decomposition (SVD)

7.3 Principal Component Analysis (PCA) and Eigenfaces